

APPLICATION
FOR
UNITED STATES OF AMERICA

SPECIFICATION

TO ALL WHOM IT MAY CONCERN:
Be it known that We,

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have invented certain improvements in

“CIRCULAR KNITTING MACHINE, PARTICULARLY OF THE
MEDIUM-DIAMETER TYPE, WITH IMPROVED NEEDLE
ACTUATION”

of which the following description in connection with the accompanying
drawings is a specification, like reference characters on the drawings
indicating like parts in the several figures.

The present invention relates to a circular knitting machine, particularly of the medium-diameter type, with improved needle actuation.

BACKGROUND OF THE INVENTION

The field of circular knitting machine has always felt the need to
5 reduce as much as possible the height of the needle cylinder so as to reduce its inertia, in order to be able to increase its rotation rate and therefore increase correspondingly the productivity of these machines.

However, this need clashes with an equally important need, which is versatility, i.e., the possibility to produce on a same machine various kinds
10 of knitting process, the execution of which often entails increasing even considerably the complexity of the needle actuation system, increasing the space occupation entailed by the installation of several accessories around the needle cylinder, which inevitably force an increase in the height of the needle cylinder, which in practice constitutes the only dimensional variable
15 that allows design freedom.

Furthermore, in circular knitting machines there has always been the need to improve the quality level of the manufactured articles. In recent years, this need has increased, also because continuous improvements have allowed these machines to produce items that increasingly approximate
20 finished items, reducing and in some times eliminating the use of subsequent processes.

Furthermore, in needle actuation systems of machines of this type it has been noted that in any kind of knitting process the heel of the needles always engages the lowering cams, i.e., the cams that lower the needle into
25 the needle cylinder after engaging the yarn at a drop or feed of the machine, even when the corresponding needle is excluded from knitting at a drop. This engagement with the lowering cams produces unwanted movements of the needle, and if the needle is holding previously formed knitting these movements can alter or even break the stitches, inevitably penalizing the
30 quality of the product.

SUMMARY OF THE INVENTION

The aim of the present invention is to solve the problems noted above by providing a circular knitting machine, particularly of the medium-diameter type, with a particularly simple needle actuation system that allows
5 to contain the axial dimensions of the needle cylinder without penalizing the range of possible types of knitting.

Within this aim, an object of the invention is to provide a machine that can operate at high rotation rates of the needle cylinder and can therefore achieve high production levels.

10 Another object of the invention is to provide a machine that thanks to a containment of the total weight of the needle cylinder and to the needle actuation system can operate without problems even in the case of medium- and large-diameter machines, with reversals of the direction of rotation of the needle cylinder, allowing types of knitting that have never been
15 performed up to now on these machines, such as for example the provision of three-dimensional shapes without necessarily having to vary the tightness of the knitting or introducing in preset regions portions of additional courses of knitting that require unsightly trimming that is negative for the fit of the product.

20 This aim and these and other objects that will become better apparent hereinafter are achieved by a circular knitting machine, which comprises a footing that supports a needle cylinder that can be rotationally actuated with respect to said footing about its own axis, which is orientated substantially vertically; a plurality of axial slots being formed on the outer lateral surface
25 of the needle cylinder, each slot accommodating a needle; means for actuating the needles being provided and interacting with said needles during the rotation of the needle cylinder about its own axis in order to actuate the needles along the corresponding axial slot of the needle cylinder so that the needles form knitting with at least one yarn dispensed to the
30 needles at at least one drop or feed of the machine, characterized in that said

needle actuation means comprise, for each needle, a sub-needle arranged in the corresponding axial slot of the needle cylinder below the corresponding needle; said sub-needle being connected bilaterally to the corresponding needle in its motion along the corresponding axial slot and having, along its extension, a heel that is orientated radially with respect to the needle cylinder; said sub-needle being able to oscillate on a radial plane of the needle cylinder in order to pass from an active position, in which it is extracted radially with its heel from the corresponding axial slot of the needle cylinder so as to engage paths formed by sub-needle actuation cams, which are arranged around the needle cylinder and are suitable to produce or allow a movement of said sub-needle along the corresponding axial slot of the needle cylinder, to an inactive position, in which it is embedded with its heel in the corresponding axial slot of the needle cylinder so as to avoid engaging said sub-needle actuation cams; actuation means being provided which act on said sub-needle for its transition from said active position to said inactive position and vice versa.

BRIEF DESCRIPTION OF THE DRAWINGS

Further characteristics and advantages of the invention will become better apparent from the description of a preferred but not exclusive embodiment of the machine according to the invention, illustrated by way of non-limiting example in the accompanying drawings, wherein:

Figure 1 is a schematic flat projection view of a portion of the cam box of the machine according to the invention, in a first operating condition;

Figure 2 is a schematic flat projection view of a portion of the cam box of the machine according to the invention in a second operating condition;

Figure 3 is a schematic flat projection view of a portion of the cam box of the machine according to the invention in a third operating condition;

Figure 4 is a schematic flat projection view of a portion of the cam box of the machine according to the invention in a fourth operating

condition;

Figure 5 is a schematic axial sectional view of the needle cylinder of the machine according to the invention, with a sub-needle in the inactive position;

5 Figure 6 is a schematic axial sectional view of the needle cylinder of the machine according to the invention, illustrating the transition of the sub-needle from the inactive position to the active position;

 Figure 7 is a schematic axial sectional view of the needle cylinder of the machine according to the invention, with the sub-needle in the active
10 position;

 Figure 8 is a schematic axial sectional view of the needle cylinder of the machine according to the invention, with the sub-needle in the active position during the lifting of the overlying needle.

DESCRIPTION OF THE PREFERRED EMBODIMENTS

15 With reference to the figures, the circular knitting machine according to the invention, generally designated by the reference numeral 1 and shown only partially and schematically, comprises, like known types of machine, a footing, which is not illustrated for the sake of simplicity and supports a needle cylinder 2, which can rotate, with respect to the footing, about its
20 own axis 2a, which is orientated substantially vertically. Multiple axial slots 3 are formed on the outer lateral surface of the needle cylinder 2 and each slot accommodates a needle 4.

 The machine comprises means for actuating the needles 4, which are described in greater detail hereinafter and interact with the needles 4 during
25 the rotation of the needle cylinder 2 about its own axis 2a in order to actuate the needles 4 along the corresponding axial slot 3 so that the needles 4 form knitting with at least one yarn, which is dispensed to the needles 4 at at least one feed or drop 5, which is arranged laterally to the axis 2a and at which appropriately provided yarn fingers 6 are positioned.

30 According to the invention, the needle actuation means comprise, for

each needle 4, a sub-needle 7, which is arranged below the corresponding needle 4 in the same axial slot 3 of the needle cylinder 2. The sub-needle 7 is connected bilaterally, in its motion along the corresponding axial slot 3, i.e., parallel to the axis 2a of the needle cylinder 2, to the overlying needle 4, and has, along its longitudinal extension, a heel 7a, which is orientated radially with respect to the needle cylinder 2. The bilateral connection between the needle 4 and the sub-needle 7 is achieved by virtue of a particular geometric coupling between the upper end of the sub-needle 7 and the lower end of the needle 4. This coupling, in addition to providing said bilateral connection, allows the sub-needle 7 to oscillate on a radial plane of the needle cylinder 2 in order to pass from an active position, in which it is extracted radially with its heel 7a from the corresponding axial slot 3 of the needle cylinder 2, to an inactive position, in which it is embedded with its heel 7a in the corresponding axial slot 3.

Sub-needle actuation cams, generally designated by the reference numeral 8, face and lie around the outer lateral surface of the needle cylinder 2, at a level that corresponds to the level of the heels 7a of the sub-needles 7, are rigidly coupled to the footing of the machine as regards rotary motion about the axis 2a, and define paths that are engaged by the heels 7a of the sub-needles 7 when they are in the active position and vice versa are not engaged by the heels 7a of the sub-needles 7 that are in the inactive position. The paths defined by the actuation cams 8 of the sub-needles 7 are shaped so as to force or allow the sub-needles 7, the heels 7a of which engage said paths, an upward or downward motion along the corresponding axial slot 3 of the needle cylinder 2 as a consequence of the rotation of the needle cylinder 2 about the axis 2a with respect to said cams 8.

The needle 4 also has, along its longitudinal extension, a heel 4a that lies radially with respect to the needle cylinder 2 and can engage paths defined by needle actuation cams, generally designated by the reference numeral 9 and rigidly coupled to the footing of the machine as regards

rotary motion about the axis 2a. Said paths are shaped so as to force or allow the needles 4, the heels 4a of which engage said paths, an upward or downward motion along the corresponding axial slot 3 of the needle cylinder 2 as a consequence of the rotation of the needle cylinder 2 about the axis 2a with respect to the cams 9.

The means for actuating the needles 4 furthermore comprise sub-needle actuation means that act on command on the sub-needle 7 in order to produce its transition from the inactive position to the active position or vice versa.

Said means for actuating the sub-needle 7 comprise, for each sub-needle 7, an actuation element 10, which is arranged in each one of the axial slots 3 below the sub-needle 7 and can move on command along the axial slot 3, i.e., parallel to the axis 2a of the needle cylinder 2, in order to interact with the lower end of the sub-needle 7 and produce its transition or retention in the inactive position or in the active position.

The actuation element 10 comprises a selector 11, which is provided, along its longitudinal extension, with at least one heel 11a, 11b that is extended radially with respect to the needle cylinder 2. In the illustrated embodiment, the selector 11 is provided with two heels, respectively a lower heel 11a and an upper heel 11b, which are mutually spaced along the longitudinal extension of the selector 11.

The selector 11 can oscillate on a radial plane with respect to the needle cylinder 2 in order to pass from an active position, in which it protrudes radially with its lower heel 11a from the corresponding axial slot 3, to an inactive position, in which it is embedded with its lower heel 11a in the corresponding axial slot 3.

The upper heel 11b is constantly extracted from the corresponding axial slot 3.

Selector actuation cams, generally designated by the reference numeral 12, are arranged so as to face and lie around the needle cylinder 2

at a level that corresponds to the level of the selectors 11, and are rigidly coupled to the footing of the machine as regards rotary motion about the axis 2a. The selector actuation cams 12 define paths that can be engaged by the upper heel 11b and by the lower heel 11a when it is in the active position. These paths are shaped so as to force or allow the selectors 11, the heels 11a, 11b of which engage said paths, an upward or downward motion along the corresponding axial slot 3 of the needle cylinder 2 as a consequence of the rotation of the needle cylinder 2 about the axis 2a with respect to the cams 12.

10 The upper heel 11b, which is constantly extracted from the corresponding axial slot 3, is used mainly to actuate the lowering of the selector 11 by means of a part of the selector actuation cams 12.

 The selectors 11 have, in a per se known manner, along their longitudinal extension, one or more selection tabs 11c, on which selection devices 43a, 43b, 43c, 43d that face the outer lateral surface of the needle cylinder 2 act on command in order to produce the transition of the corresponding selector 11 from the active position to the inactive position. Transition of the selectors 11 from the inactive position to the active position can be achieved in a manner similar to what occurs for oscillating selectors in known types of machine, for example by virtue of extraction cams 13, which are arranged proximate to the lower end of the needle cylinder 2 and act on the lower end of the selectors 11. The selection devices, as well as the extraction cams 13, are arranged upstream of each drop 5 of the machine along the direction of rotation of the needle cylinder 2 about its own axis 2a with respect to the cam box.

 The lower end of the sub-needle 7 is conveniently shaped complementarily with respect to the upper end of the actuation element 10, so that a movement of the actuation element 10 along the corresponding axial slot 3 of the needle cylinder 2 produces the transition of the sub-needle 7 from the inactive position to the active position or vice versa.

Conveniently, the lower end of the sub-needle 7 has a forked shape, in which a first prong 14a protrudes downward with respect to the second prong 14b.

5 The first prong 14a is furthermore closer to the bottom, i.e., to the wall directed toward the axis 2a, of the corresponding axial slot 3, than the second prong 14b. The first prong 14a can be engaged by an upper portion of the actuation element 10 in order to move or stably retain the sub-needle 7 in its inactive position, while the second prong 14b can be engaged by the upper portion of the actuation element 10 in order to move or stably retain
10 the sub-needle 7 in the active position.

Furthermore, the upper portion of the actuation element 10 can be inserted between the two prongs 14a, 14b of the lower end of the sub-needle for the very purpose of reinforcing the retention of the sub-needle 7 in the active position.

15 Conveniently, the actuation element 10 comprises, in addition to the selector 11, a pusher 15, which is accommodated so that it can slide within the corresponding axial slot 3 of the needle cylinder 2 between the selector 11 and the sub-needle 7.

In practice, the upper portion of the actuation element 10 that engages
20 the lower end of the sub-needle 7 is constituted by the upper portion of the pusher 15.

The pusher 15 has, along its longitudinal extension, a heel 15a that protrudes from the corresponding axial slot 3 of the needle cylinder 2 and can engage paths formed by pusher actuation cams, generally designated by
25 the reference numeral 16, which are rigidly coupled to the footing of the machine as regards rotation about the axis 2a. The paths defined by the actuation cams 16 of the pushers are shaped so as to force or allow the pushers 15, the heels 15a of which engage said paths, an upward or downward motion along the corresponding axial slot 3 of the needle
30 cylinder 2 as a consequence of the rotation of the needle cylinder 2 about

the axis 2a with respect to the cams 16.

The upper portion of each pusher 15 has, in a region that is spaced downward from the upper end of said pusher 15, a first region 17, which forms an inclined plane with respect to the longitudinal extension of the corresponding axial slot 3 and can engage a corresponding region 18 that forms an inclined plane and is provided at the lower end of the first prong 14a of the fork of the sub-needle 7, in order to achieve the transition of the sub-needle 7 from the active position to the inactive position as a consequence of the downward movement of the pusher 15 along the corresponding axial slot 3 of the needle cylinder 2.

The upper portion of each pusher 15 furthermore has, at its upper end, a second region 19, which forms an inclined plane with respect to the longitudinal extension of the corresponding axial slot 3 and can engage a corresponding region 20, which forms an inclined plane and is provided at the lower end of the second prong 14b of the fork of the sub-needle 7, in order to achieve the transition of the sub-needle 7 from the inactive position to the active position as a consequence of the upward movement of the pusher 15 along the corresponding axial slot 3 of the needle cylinder 2.

At the fork of the lower end of the sub-needles 7, the axial slots 3 have, on their bottom, a recessed region 25 for containing said fork and for allowing the oscillation of the sub-needle 7. Optionally, the upper part of said recessed region 25 may be shallower than the remaining part, so as to form a support for the forked region at least in the condition of maximum lifting of the sub-needle 7 that retains it stably in the active position.

The paths defined by the selector actuation cams 12 have, ahead of each drop 5 along the direction of rotation of the needle cylinder 2 about the axis 2a with respect to the cam box, a first rising portion 21 and a second rising portion 22, in which the peak is higher than the peak of the first rising portion 21 in order to produce lifting respectively up to a tuck-stitch lifting level and to a drop-stitch lifting level for the overlying needle 4. The rising

portions 21 and 22 are designed to be engaged by the lower heel 11a of the selectors 11 in the active position.

Ahead of each drop or feed 5 of the machine along the direction of rotation of the needle cylinder 2 about its own axis 2a with respect to the cam box, four selection devices are provided: two of said devices are located between the first rising portion 21 and the second rising portion 22.

Preferably, the knitting forming cams, also known as lowering cams, i.e., the cams that produce the descent of the needles after engaging the yarn at a drop, in the machine according to the invention, are part of the actuation cams 8 of the sub-needles 7.

The lowering cams can be movable on command, in a per se known manner, parallel to the axis 2a in order to vary the tightness of the knitting.

Preferably, the machine according to the invention has four drops or feeds 5, which are mutually angularly spaced around the axis 2a of the needle cylinder 2.

In the machine according to the invention, the needle actuation means allow to simplify the cam box and the accessory elements that are usually arranged around the needle cylinder and at the same time allow to perform substantially all the knitting processes currently possible in knitting machines, obtaining qualitatively superior results, as well as knitting processes that currently cannot be obtained on circular knitting machines having a medium diameter or more specifically having a diameter substantially comprised between 7 and 24 inches.

Without altering the fact that the machine according to the invention, with its particular needle actuation means, may be provided with any diameter and as a machine in which the needle cylinder can be actuated with a rotary motion in a single direction of rotation without thereby abandoning the scope of the protection of the present invention, the particular means for the actuation of the needles of the machine according to the invention allow to contain the height and therefore the inertia of the needle cylinder,

allowing its rotary actuation about its axis 2a in both directions of rotation. Said means for the actuation of the needles 4, in view of the way in which they are structured, can be used to allow the needles 4 to form knitting in both directions of rotation of the needle cylinder 2 about its own axis 2a at
5 at least one drop 5.

The embodiment of the machine according to the invention shown in the accompanying drawings indeed refers to a machine with a needle cylinder 2 which, depending on the knitting requirements, can be actuated with a continuous motion in one direction of rotation or in the opposite
10 direction or with an alternating motion (or oscillating motion) about its own axis 2a.

In this embodiment, at at least one drop and preferably at each drop, there are two mutually opposite lowering cams 23 and 24 for lowering the needles after the yarn has been engaged at the drop being considered; said
15 cams are designed to be used respectively in the rotary motion of the needle cylinder 2 in one direction or in the opposite direction.

It is possible to use, for the actuation of the needle cylinder 2 with a rotary motion about its own axis 2a, an electric motor of a known type that allows to reverse the rotation of its output shaft, or said rotary motion
20 reversal can be achieved by virtue of a transmission interposed between the motor and the needle cylinder 2.

The needle cylinder 2 can be provided, in a per se known manner, with means for controlling its angular position about the axis 2a, such as for example devices such as encoders or the like, so as to allow to control the
25 position of the various needles 4 about the axis 2a during the rotation of the cylinder 2.

The machine is preferably provided with an actuation and control element of the programmable electronic type, which supervises the operation of the various elements of the machine so as to be able to perform
30 knitting according to preset programs.

The means for actuating the needles 4, described earlier, can be used to actuate the needles 4 so that they form knitting in both directions of the rotation of the needle cylinder 2 about its own axis 2a at all the drops 5.

5 Figures 1 to 4, described in greater detail hereinafter, illustrate in a flat projection view a portion of the cam box of the machine. The illustrated portion relates to a little more than one drop 5, and preferably this configuration of the cams is repeated as regards the other drops of the machine.

In practice, in a machine equipped with needles and needle actuation
10 means according to the invention and meant to be used to form knitting in both directions of rotation of the needle cylinder 2 about its own axis 2a, the arrangement and configuration of the needle actuation cams 9, of the sub-needle actuation cams 8, of the pusher actuation cams 16 and of the selector actuation cams 12 is preferably symmetrical with respect to a radial plane of
15 the needle cylinder that passes through a drop or feed. A similar symmetry also occurs in the arrangement of the selection devices 43a, 43b, 43c, 43d.

The machine is completed with the elements that are usually present in circular knitting machines of this type, such as for example sinkers, fabric tensioning devices, various control systems, etcetera.

20 Optionally, the machine can be equipped with needles 4, sub-needles 7 and pushers 15 that have mutually different heel lengths.

Merely by way of example, Figures 1 to 4 illustrate four different operating conditions of a needle of the machine according to the invention. The direction of rotation of the needle cylinder 2 in the various figures is
25 indicated by the arrow 30. The portions of the paths of the heels of the various elements in the active position have been shown by means of solid bars, while the portions of the paths of the heels of the various elements in the inactive position have been shown by means of broken lines. The needle 4, the sub-needle 7, the pusher 15 and the selector 11 have been shown,
30 laterally with respect to the cam box portion, turned through 90° in a merely

exemplifying position, since the position of these elements can vary according to the imparted actuation, as described below.

Figure 1 illustrates the condition in which the needle is excluded from knitting at a drop or feed 5 of the machine. To achieve this condition, the selector 11 of the needle 4 being considered is retained in the inactive position by way of the selection devices. In this manner, the pusher 15, ahead of the drop being considered, is first lowered together with the sub-needle 7 and then returned to the lowermost position, causing the transition of the sub-needle 7 to the inactive position. In this manner, the corresponding needle 4 passes with its head below the lowering plane of the sinkers of the machine.

It should be noted that in this operating condition the heel 7a of the sub-needle 7 does not engage the lowering cams 23, 24, thus avoiding even small movements of the needle excluded from knitting, which occur in known types of machine and cause accidental breakage of the fabric when the needles that are excluded from knitting at the feed being considered carry knitting formed at other feeds of the machine.

Figure 2 illustrates the actuation of a needle 4 for forming a drop stitch.

In this case, the selector 11 of the needle 4 being considered is retained or moved into the active position by means of the selection devices so that its lower heel 11a engages both the rising portion 21 and the rising portion 22 of the path defined by the cams 12. In this manner, the pusher 15, after being lifted by the upward motion of the selector 11 engaged with the first rising portion 21 and assisted by a cam 31 of the actuation cams 16 of said pusher 15, is lowered by a cam 32 that again belongs to the cams 16 and causes the momentary transition of the sub-needle 7 into the inactive position in order to allow it to move beyond the lowering cam 23 without engaging it. The additional lifting produced by the engagement of the pusher 15 with the cam 33, which again belongs to the actuation cams 16 of

the pusher 15, and of the selector 11 with the rising portion 22, produces the lifting of the needle 4 up to the point where the previously formed loop of knitting is dropped onto the stem of the needle 4 before the needle 4 takes the yarn dispensed at the drop being considered and begins a new descent.

5 Figure 3 illustrates the actuation of a needle to form a tuck stitch.

In this case, the selector 11, by virtue of the selection devices, is engaged only with the rising portion 21. In this manner, the pusher 15 behaves as in Figure 2, except that at the drop 5 it does not receive the further upward motion that would be produced by the engagement of the selector 11 with the cam 22. For this reason, the needle 4 is raised to a lesser extent, and the loop of knitting is not dropped onto the stem of the needle 4 before taking a new yarn at the drop or feed being considered, but remains in the hook of the needle 4, which forms a new loop of knitting.

Figure 4 illustrates the actuation of a needle to form a floated stitch.

15 In this case, the actuation of the various elements is similar to the one described with reference to Figure 2, except that a movable cam 35 is inserted so as to act between the pusher actuation cams 16, causing a greater lifting of the needle 4 before it reaches the drop 5. Said greater lifting of the needle 4 has the effect of causing the transfer of the previously formed loop of knitting onto the stem of the needle 4 below the latch. In this condition, the needle 4 can then be actuated, by way of the selection device 43d, so as to reach a drop-stitch level, or can be retained at a tuck-stitch level. These two levels of lifting of the needle 4 can be used to make the needle engage different yarns dispensed at the drop 5, for example in order to make it engage two yarns when performing drop-stitch lifting and a single yarn when performing tuck-stitch lifting.

Figure 4 illustrates the lifting of the needle 4 to the drop-stitch level.

It should be noted that in the machine according to the invention, the needle actuation means, constituted by the sub-needles, pushers and selectors, and the arrangement and distribution of the functions of the

actuation cams of these elements allow to have as many as four selection points, two for each direction of rotation of the needle cylinder about its own axis, at each feed of the machine, with selection devices that can be arranged at the same vertical elevation.

- 5 Furthermore, the set of needle actuation means allows to contain considerably the height of the needle cylinder and therefore to contain the inertia of the needle cylinder, allowing its actuation with an alternating rotary motion, even at relatively high speeds, about its own axis.

10 The possibility to rotationally actuate the needle cylinder in both directions of rotation and in particular the possibility to actuate the needle cylinder with an alternating rotary motion about its own axis allows to produce without problems three-dimensional shapes on the tubular articles that can produced with the machine, and to produce reinforced regions without varying the tightness of the knitting and without having to produce
15 portions of courses of knitting to be trimmed.

 In alternating motion, for producing contoured pouches, it is possible to perform knitting with progressive increases and decreases of the active needles simply by using the needle selection possibilities offered by the machine with adequate programming of the operation of the selection
20 devices.

 In addition to these possibilities, the machine according to the invention is capable of producing intarsia knitting, plated fabrics, Jacquard knitting on three technical tracks, striped fabrics, tuck-stitch knitting and floated-stitch knitting.

- 25 In practice it has been found that the machine according to the invention fully achieves the intended aim, since the particular needle actuation system allows to simplify the cam box, to contain the vertical space occupation of the needle cylinder, to perform the knitting processes that can be performed by currently commercially available machines and
30 also knitting processes that currently cannot be obtained in medium-

diameter circular machines.

In particular, the needle actuation system of the machine according to the invention is suitable to be used to perform needle cylinder actuation in both directions of rotation, allowing to produce, even on medium- and large- diameter machines, articles that have three-dimensional shapes without necessarily resorting to variations in the tightness of the knitting and without requiring the execution of additional portions of courses with yarn trimming. The machine according to the invention also allows to perform intarsia knitting, i.e., knitting with colored designs without floated yarns on the reverse side.

The machine according to the invention is therefore capable of producing items of clothing of superior quality with respect to what can be achieved with circular knitting machines of a conventional type.

The machine thus conceived is susceptible of numerous modifications and variations, all of which are within the scope of the appended claims; moreover, all the details may be replaced with other technically equivalent elements.

In practice, the materials used may be any according to requirements and to the state of the art.

The disclosures in Italian Patent Application No. MI2003A000899 from which this application claims priority are incorporated herein by reference.

CLAIMS

1. A circular knitting machine, comprising a footing that supports a needle cylinder (2) that can be rotationally actuated, with respect to said footing about its own axis (2a), which is orientated substantially vertically; a plurality of axial slots (3) being formed on the outer lateral surface of the needle cylinder (2), each slot (3) accommodating a needle (4); means (7,8,9,10) for actuating the needles (4) being provided and interacting with said needles (4) during the rotation of the needle cylinder (2) about its own axis (2a) in order to actuate the needles (4) along the corresponding axial slot (3) of the needle cylinder (2) so that the needles (4) form knitting with at least one yarn dispensed to the needles (4) at at least one drop or feed (5) of the machine, characterized in that said needle actuation means comprise, for each needle, a sub-needle (7) arranged in the corresponding axial slot (3) of the needle cylinder (2) below the corresponding needle (4); said sub-needle (7) being connected bilaterally to the corresponding needle (4) in its motion along the corresponding axial slot (3) and having, along its extension, a heel (7a) that is orientated radially with respect to the needle cylinder (2); said sub-needle (7) being able to oscillate on a radial plane of the needle cylinder (2) in order to pass from an active position, in which the sub-needle (7) is extracted radially with its heel (7a) from the corresponding axial slot (3) of the needle cylinder (2) so as to engage paths formed by sub-needle actuation cams (8), which are arranged around the needle cylinder (2) and are suitable to produce or allow a movement of said sub-needle (7) along the corresponding axial slot (3) of the needle cylinder (2), to an inactive position, in which it is embedded with its heel (7a) in the corresponding axial slot (3) of the needle cylinder (2) so as to avoid engaging said sub-needle actuation cams (8); sub-needle actuation means (10) being provided which act on said sub-needle (7) for its transition from said active position to said inactive position and vice versa.

2. The machine according to claim 1, characterized in that said needle

has, along its extension, a heel that protrudes radially with respect to the needle cylinder and can engage paths formed by needle actuation cams that are arranged around the needle cylinder and are suitable to produce or allow movement of the needle along the corresponding axial slot of the needle
5 cylinder.

3. The machine according to claim 1, characterized in that said means for actuating the sub-needle comprise an actuation element that is arranged in each one of said axial slots below the corresponding sub-needle and can move on command along the corresponding axial slot in order to interact
10 with the lower end of the sub-needle and produce the transition and retention of said sub-needle in said active position or in said inactive position.

4. The machine according to one or more of the preceding claims, characterized in that said actuation element comprises an oscillating
15 selector, which is provided, along its extension, with at least one heel that protrudes radially with respect to the needle cylinder, said selector being able to oscillate on a radial plane with respect to the needle cylinder in order to pass from an active position, in which it protrudes radially with its heel from the needle cylinder so as to engage paths defined by selector actuation
20 cams arranged around the needle cylinder and suitable to produce or allow a movement of the selector along the corresponding axial slot of the needle cylinder, to an inactive position, in which it is embedded with its heel in the corresponding axial slot of the needle cylinder so as to avoid engaging said selector actuation cams, and vice versa, at least one selection device that
25 acts on command on said selector for its transition or retention in said active position or in said inactive position being provided for each one of said drops or feeds.

5. The machine according to one or more of the preceding claims, characterized in that said needle cylinder can be actuated with a rotary
30 motion about its own axis in both directions of rotation, and in that said

needle actuation means are suitable to allow the needles to form knitting in both directions of rotation of the needle cylinder about its own axis, at at least one drop or feed of the machine.

6. The machine according to one or more of the preceding claims,
5 characterized in that said needle cylinder can be actuated with an alternating rotary motion about its own axis.

7. The machine according to one or more of the preceding claims,
characterized in that for each one of said drops or feeds four selection
10 devices are provided, two for each direction of rotation of the needle cylinder about its own axis, said devices acting on command on said selector for its transition or retention in said active position or in said inactive position.

8. The machine according to one or more of the preceding claims,
characterized in that the lower end of said sub-needle is shaped
15 complementarily to the upper end of said actuation element in order to move said sub-needle from said inactive position to said active position or vice versa as a consequence of an axial movement of said actuation element along the corresponding axial slot of the needle cylinder.

9. The machine according to one or more of the preceding claims,
20 characterized in that the lower end of said sub-needle is forked, with a first prong that protrudes downward with respect to the second prong; said first prong lying closer to the bottom of the corresponding axial slot of the needle cylinder than said second prong; said first prong being engageable by an upper portion of said actuation element to move or stably retain said sub-
25 needle in its inactive position, and said second prong being engageable by said upper portion of said actuation element to move or stably retain said sub-needle in the active position.

10. The machine according to one or more of the preceding claims,
characterized in that said upper portion of said actuation element can be
30 inserted, in the motion of said actuation element along the corresponding

axial slot of the needle cylinder, between the two prongs of the fork of the lower end of said sub-needle.

11. The machine according to one or more of the preceding claims, characterized in that said upper portion of said actuation element has, in a
5 region that is spaced from the upper end of said upper portion, a first region that forms an inclined plane with respect to the longitudinal extension of the corresponding axial slot of the needle cylinder and can engage a corresponding region that forms an inclined plane and is provided at the lower end of said first prong of the fork of the sub-needle for the transition
10 of said sub-needle from said active position to said inactive position as a consequence of the downward movement of said actuation element along the corresponding axial slot of the needle cylinder.

12. The machine according to one or more of the preceding claims, characterized in that the upper portion of said actuation element has, at its
15 upper end, a second region that forms an inclined plane with respect to the longitudinal extension of the corresponding axial slot of the needle cylinder and can engage a corresponding region that forms an inclined plane and is provided at the lower end of said second prong of the fork of the sub-needle for the transition of said sub-needle from said inactive position to said
20 active position as a consequence of the upward movement of said actuation element along the corresponding axial slot of the needle cylinder.

13. The machine according to one or more of the preceding claims, characterized in that said actuation element comprises, in addition to said selector, a pusher that is accommodated so that it can slide in the
25 corresponding axial slot of the needle cylinder between said selector and said sub-needle, said upper portion of the actuation element that can engage the lower end of said sub-needle being constituted by the upper portion of said pusher.

14. The machine according to one or more of the preceding claims,
30 characterized in that said pusher has, along its extension, a heel that

protrudes from the corresponding axial slot of the needle cylinder and can engage paths that are defined by pusher actuation cams arranged around the outer lateral surface of the needle cylinder and are shaped so as to produce a motion of said pushers along the corresponding axial slots of the needle
5 cylinder.

15. The machine according to one or more of the preceding claims, characterized in that said sub-needle actuation cams comprise lowering cams to produce the downward movement of the needles after engaging the yarn at each one of said drops or feeds.

10 16. The machine according to one or more of the preceding claims, characterized in that the paths defined by said selector actuation cams have, ahead of each drop or feed, a first rising portion and a second rising portion whose peak is higher than the peak of said first rising portion for the upward movement of the needles respectively to a tuck-stitch lifting level and to a
15 drop-stitch lifting level for the overlying needle, at least one selection device being interposed between said first rising portion and said second rising portion.

17. The machine according to one or more of the preceding claims, characterized in that two selection devices are arranged sequentially
20 between said first rising portion and said second rising portion of the selector actuation cams and can be used selectively depending on the direction of rotation of the needle cylinder about its own axis.

18. The machine according to one or more of the preceding claims, characterized in that the bottom of each axial slot of the needle cylinder has
25 a portion that can be engaged by said sub-needle at least in its fully lifted condition in order to retain said sub-needle in its active position.

19. The machine according to one or more of the preceding claims, characterized in that said selection devices are arranged at a same height.

20. The machine according to one or more of the preceding claims,
30 characterized in that it comprises four drops or feeds, which are angularly

mutually spaced around the axis of the needle cylinder.

21. The machine according to one or more of the preceding claims, characterized in that said needle actuation means are suitable to allow the needles to form knitting in both directions of rotation of the needle cylinder
5 about its own axis at each one of the drops or feeds.

22. The machine according to one or more of the preceding claims, characterized in that said needle actuation cams, said sub-needle actuation cams, said pusher actuation cams and said selector actuation cams have configurations and arrangements that are symmetrical with respect to a
10 radial plane of the needle cylinder that passes through a drop or feed.

23. The machine according to one or more of the preceding claims, characterized in that said selection devices are arranged symmetrically with respect to a radial plane of the needle cylinder that passes through a drop or feed.

15 24. The machine according to one or more of the preceding claims, characterized in that said needle cylinder has a diameter that is substantially comprised between 7 and 24 inches.

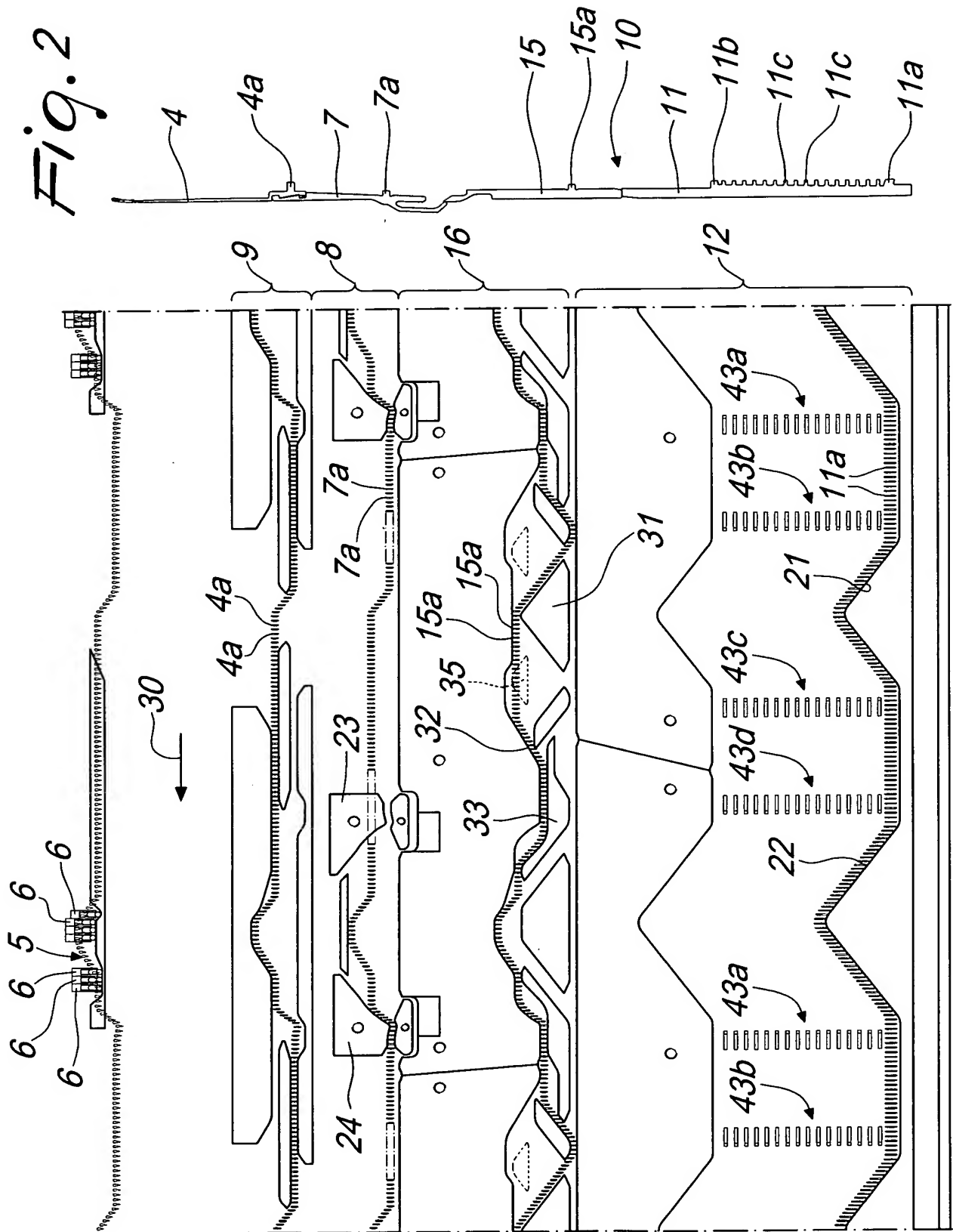
CIRCULAR KNITTING MACHINE, PARTICULARLY OF THE
MEDIUM-DIAMETER TYPE, WITH IMPROVED NEEDLE
ACTUATION

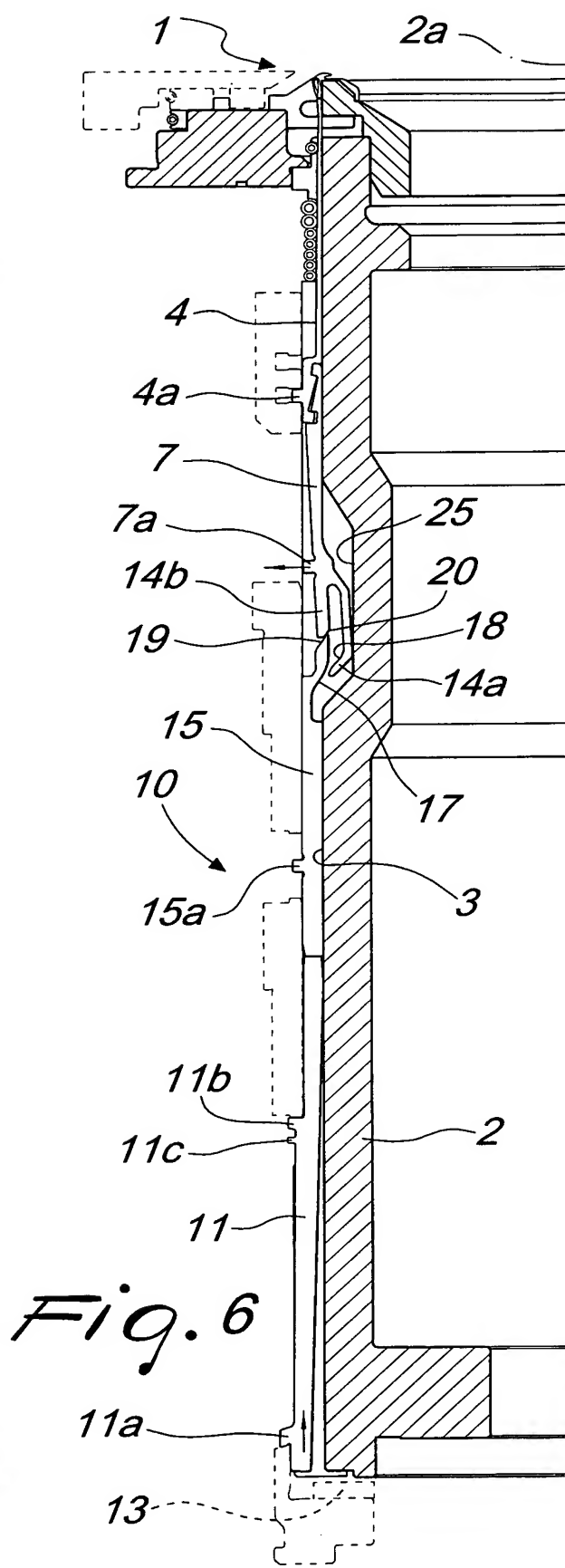
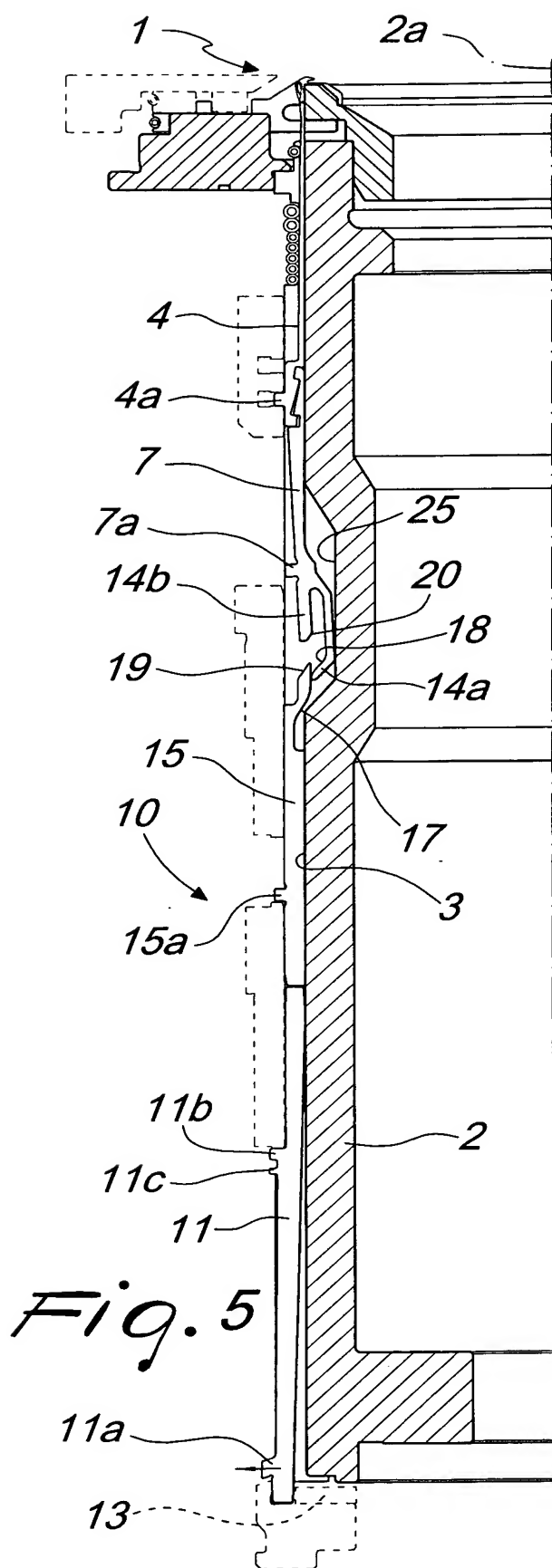
ABSTRACT

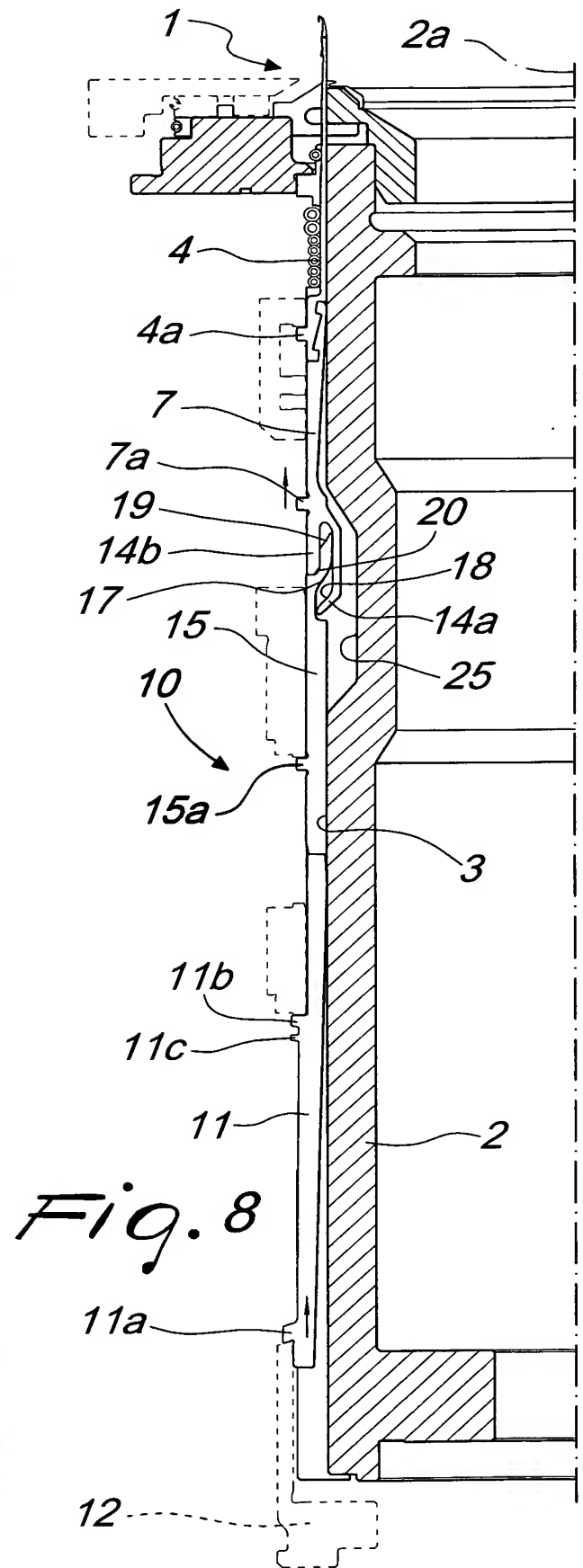
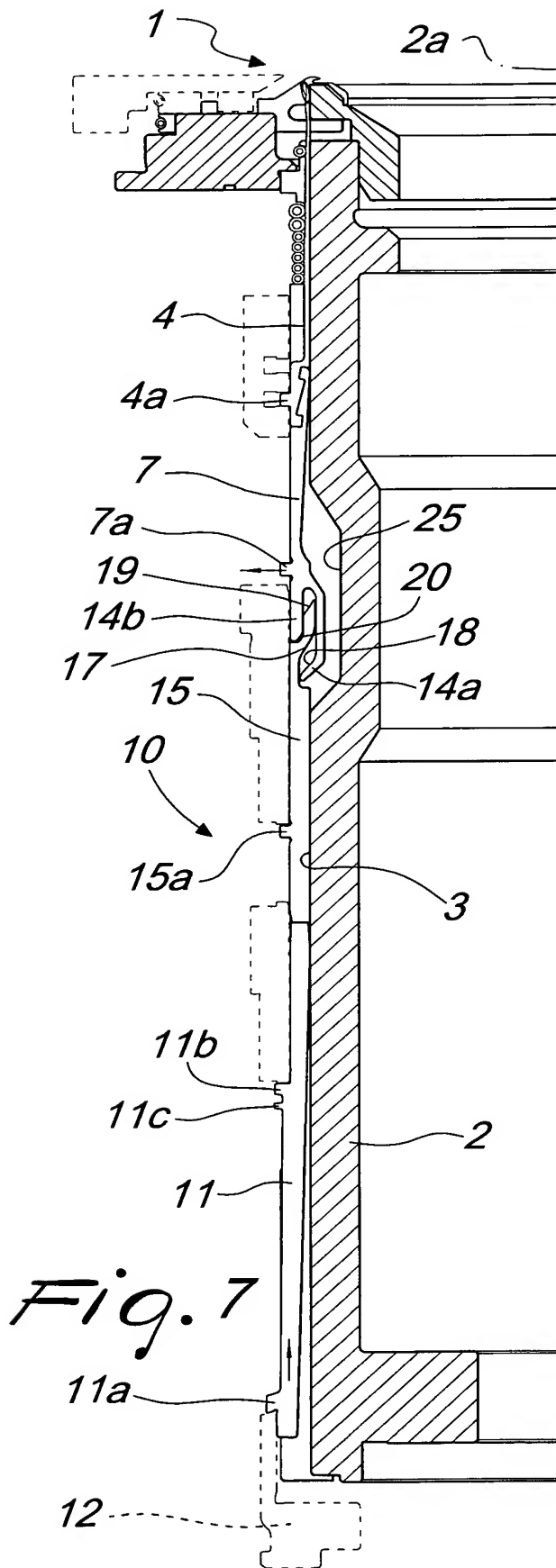
5 A circular knitting machine, particularly of the medium-diameter
type, with improved needle actuation, which comprises a footing that
supports a needle cylinder (2) rotationally actuatable with respect to the
footing about its own axis (2a), which is orientated substantially vertically;
multiple axial slots (3) formed on the outer lateral surface of the needle
10 cylinder (2), each slot (3) accommodating a needle (4); a sub-needle (7)
arranged below each needle (4) in a corresponding axial slot (3) and
connected bilaterally to the corresponding needle (4) in its motion along the
corresponding axial slot (3) and having, along its extension, a heel (7a)
orientated radially with respect to the needle cylinder (2), the sub-needle
15 being oscillatable on a radial plane of the needle cylinder (2) in order to
pass from an active position, in which it is extracted radially with its heel
(7a) from the corresponding axial slot (3) of the needle cylinder (2) so as to
engage paths formed by sub-needle actuation cams (8), which are arranged
around the needle cylinder (2) and are suitable to produce or allow a
20 movement of the sub-needle (7) along the corresponding axial slot (3) of the
needle cylinder (2) in order to actuate the overlying needle (4), to an
inactive position, in which it is embedded with its heel (7a) in the
corresponding axial slot (3) of the needle cylinder (2) so as to avoid
engaging the sub-needle actuation cams; and a sub-needle actuation (10),
25 which act on the sub-needle (7) for its transition from the active position to
the inactive position and vice versa.

(Figure 7)

Fig. 2







INTERNATIONAL SEARCH REPORT

International Application No
PCT/EP2004/004476

A. CLASSIFICATION OF SUBJECT MATTER
IPC 7 D04B15/68

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)
IPC 7 D04B

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the International search (name of data base and, where practical, search terms used)
EPO-Internal

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category *	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 3 990 270 A (PAEPKE HORST) 9 November 1976 (1976-11-09) column 2, line 48 - column 3, line 59; figures 1-5	1-4, 8, 15, 18-20
Y	column 9, line 45 - column 10, line 17; figures 9-14	
Y	column 2, line 68 - column 3, line 2	5, 6, 19-24
Y	GB 1 416 179 A (LONATI COST MECC) 3 December 1975 (1975-12-03) page 5, lines 3-123; claims 12, 14; figure 4	5, 6, 19-24

☐ Further documents are listed in the continuation of box C.

☒ Patent family members are listed in annex.

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Date of the actual completion of the international search

28 September 2004

Date of mailing of the international search report

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INTERNATIONAL SEARCH REPORT

International Application No
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